





DentaDrive X.0

High Frequency Spindle

Pneumatic direct change



Identification of HF spindle



As we always ensure that our HF spindles are at the cutting edge of technological development, we reserve the right to make technical modifications and variations from the exact design described in the manual.



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1

Preliminary information

The high frequency spindle (HF spindle) is a high quality precision tool for high speed machining.

1.1 Purpose of the manual

The manual is an important component of the HF spindle.

- Store the manual carefully.
- Make the manual available to all persons who work with the HF spindle.
- Read the documentation supplied in full.
- Before carrying out any work, read the corresponding section of the manual carefully again.

Explanation of symbols used

To enable quick classification of information, this manual uses visual aids in the form of symbols and text markings.

Notes are marked with a signal word and a colored box:



1.2

DANGER

Dangerous situation!

Results in serious injury or death.

Measure to avert the danger.



WARNING

Dangerous situation!

May result in serious injury or death.

Measure to avert the danger.



CAUTION

Dangerous situation!

May result in minor to moderate injury.

Measure to avert the danger.



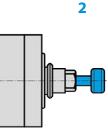
Note

May result in material damage. This warning symbol is not a warning for personal injury.

Tip

Tips indicate useful information for users.





2.1

Example of design: Inserting the shank

Transport and packaging

Note: Ensure functionality

When transporting the HF spindle, always fit an appropriate shank in the collet.

Avoid strong vibrations or impacts during transportation, as these could damage the ball bearings of the HF spindle.

- Solution ⇒ Any damage reduces the accuracy of the HF spindle.
- Any damage restricts the functionality of the HF spindle.
- Any damage shortens the service life of the HF spindle.

Scope of supply of HF spindle

The following parts are supplied with the HF spindle:

- □ High Frequency Spindle
- Hose connections
- □ Transport packaging
- Check the high frequency spindle for completeness upon delivery.

2.1.1 Optional accessories

Available on request:

- Spindle holder
- □ Frequency converter
- Collet
- Service set
- Operating hours counter
- □ Further accessories on request.

Only approved accessories have been tested for operational safety and functionality.

- Do not use any other accessories this may invalidate any warranty claims and compensation claims for damages.
- If the spindle holder is to be produced in-house, it is essential to contact Nakanishi Jaeger GmbH before starting production to request the tolerances and production plan for the spindle holder.



2.1.2 Documentation supplied

The documents listed below are supplied with the HF spindle:

- Manual
- Declaration of Incorporation
- □ Inspection protocol
- Check that the documentation supplied is complete when the spindle is delivered. If necessary, request a new copy.



Packaging of HF spindle

All transport packaging materials can be recycled in appropriate disposal facilities.



3

Designated use

The HF spindle is an "incomplete machine" in accordance with the Machinery Directive and cannot perform any function independently. The HF spindle can only be operated in conjunction with a machine tool and a frequency converter.

3.1 Permissible types of machining

The HF spindle has been developed only for the following types of machining.

- Cutting
- Drilling
- Engraving
- Grinding
- Contact Nakanishi Jaeger GmbH if other types of machining are required.

3.2 Permissible materials

The HF spindle has been developed only for the following materials.

- □ Metals (such as alloys, cast metals etc.)
- Sintered materials
- Plastics
- 🛛 Wood
- Graphite
- □ Stone (marble, etc.)
- Paper and cardboard
- Circuit boards
- Glass and ceramic
- Contact Nakanishi Jaeger GmbH if other materials are to be machined.



4

Safety instructions

The high frequency spindle is a state of the art product and is safe to operate.

However, the HF spindle may pose a risk in the following cases:

- □ If it is installed by untrained personnel.
- □ If it is used incorrectly.
- □ If it is not used in accordance with its intended use.

The high frequency spindle may only be installed, commissioned, and maintained by specialist personnel.

Definition: Specialist personnel are persons who are familiar with the assembly, installation, commissioning, and operation of the product and have the relevant qualifications for their area of activity. The operator must closely control the responsibility, training, and monitoring of these personnel.



DANGER: Due to explosion.

HF spindles are not approved for use in areas at risk of explosion. Use in such areas may result in explosions.

Do not use the HF spindle in potentially explosive atmospheres.



DANGER: Due to flying parts.

The HF spindle operates at high speeds and may therefore be flung away by these.

Operate the HF spindle only if it is installed in the machine or system in a fixed manner.



Note: Adhere to the limit values.

Observe the limit values specified in the technical data.



Note: Take account of the machine.

- Observe the manual of the machine in which the HF spindle is installed.
- Observe all safety instructions specified by the machine manufacturer.
- Ensure that the machine does not cause any hazards (e.g. uncontrolled movements). Do not install the HF spindle in the machine until this has been done.



Note. Do not damage the HF spindle.

- Any damage reduces the accuracy of the HF spindle.
- Any damage restricts the functionality of the HF spindle.
- Any damage shortens the service life of the HF spindle.



Safe working

4.1

Observe all safety instructions set out in the manual, the applicable national accident prevention regulations, and the valid company work, operation, and safety guidelines.

DANGER: Due to flying parts.

Tools that are not clamped correctly will be flung away by the centrifugal forces that occur during machining.

- ▶ Use the full clamping depth of the collet.
- Clamp the tool securely.

DANGER: Due to flying parts.

If the wrong rotational direction is used, the clamping system releases and the tool is flung away.

It is essential to adhere to the rotational direction of the HF spindle.

WARNING: Risk of injury due to flying parts.

The HF spindle operates at high speeds which may cause chips to fly out with great force.

- Never remove the protective devices of the machine or system.
- Always wear protective goggles during work.

Note: Ensure functionality.

Never operate the HF spindle without a clamped tool shank.

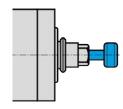
If no tool shank is clamped:

- □ The clamping system is damaged by the centrifugal forces.
- □ The clamping system is shifted.
- □ The balance of the HF spindle is affected.
- □ The bearing is damaged.
- Take the relevant measures to protect against splashes and spray according to the type of machining, the type of material being machined, and the type of tool selected.
 - b Observe the manual of the machine in which the HF spindle is installed.
- Obtain the maximum circumferential speeds of the tools used from the tool supplier.

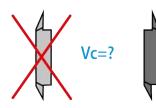
Single-point tools are not suitable for high speed cutting.

If they are required for production reasons:

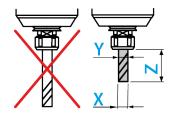
- Only use a balanced tool.
 - 🌭 DIN ISO 1940
 - Salance grade 2,5



Example of design: Inserting the shank







4.2

The tool cutting diameter (X) must not be greater than the maximum clamping range (Y).

- Always clamp the tool so that it is as short as possible.
- Skeep the dimension (Z) small.
 - ♦ (Y) See section: Technical Specifications [▶ 16].

Shutdown of HF spindle

The procedure for shutting down the high frequency spindle for installation and maintenance work is as follows:

- Completely disconnect the power supply.
- Completely disconnect the media supply (air and liquid).
- Make sure that the shaft of the HF spindle has come to an absolute standstill.

If the HF spindle is being shut down to be cleaned:

Reconnect only the sealing air.

Tip: Forward the data to the controller.

Use the option on the frequency converter of detecting the shutdown signal from the shaft and forwarding this to the machine controller for evaluation.

4.3 Installation and maintenance

- Carry out installation, cleaning, and maintenance work only after shutting down the HF spindle and after the shaft has come to a standstill.
- Install all safety and protective devices of the machine immediately after completing work.

4.4 Modification and repair

Modifications or alterations to the HF spindle are only permitted after prior consultation with **Nakanishi Jaeger GmbH**.

Only the service partners listed in the "Service and repair [> 39]" section are authorized to open and repair the HF spindle.

Only approved accessories have been tested for operational safety and functionality.

4.5 Improper operation

The high frequency spindle is only safe to operate for its designated use.

Observe the safety instructions in all sections of the manual to prevent hazards to persons, the environment, the machine, or the HF spindle itself.

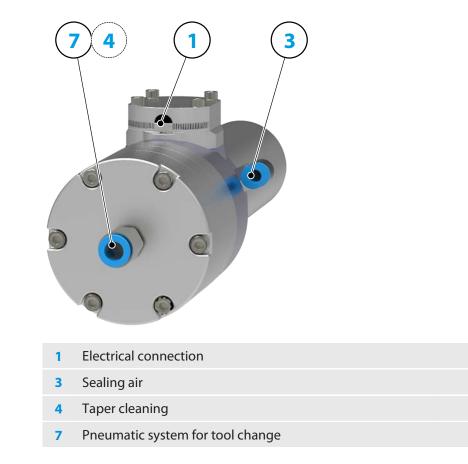
Failure to observe the safety instructions may invalidate any warranty claims and compensation claims for damages.



Technical description

5 Technical description

5.1 Connections of HF spindle



M5

M5

M5



5.2

Electrical connection

The HF spindle may only be operated with a frequency converter (FC).

- Check whether the current, voltage, and frequency data of the HF spindle match the raw data for the frequency converter.
- Use a motor supply line that is as short as possible.
- ➡ Adjust the speed of the HF spindle using the FC.
- **C** Refer to the frequency converter manual for further information.

The FC detects the following operating states of the HF spindle, depending on the version:

- □ HF spindle rotating.
- □ HF spindle too hot.
- □ HF spindle at a standstill, etc.

The FC forwards the operating states of the HF spindle to the machine controller.



Cooling

5.3

The HF spindle does not feature built-in cooling. However, this means that it has a lower power than an HF spindle with cooling.

Note: Ensure functionality.

The HF spindle is cooled by the sealing air flowing through.

- □ Always switch on the sealing air as soon as the machine enters operation.
- □ Sealing air temperature: max. 25°C.

If this is not observed, the HF spindle will be damaged or destroyed.

Note: Extension of the service life through heat dissipation.

Heat is produced during operation of the HF spindle. The temperature of the HF spindle should not exceed + 60° C as this shortens the service life of the bearing.

- Check the temperature of the HF spindle on the housing.
- Dissipate the heat using the spindle holder.

Cooling via spindle holder



5.3.1

Example of design: Air-cooled spindle holder

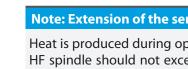


Example of design: Liquid-cooled spindle holder

To increase the power of the HF spindle, the heat generated must be dissipated via the spindle holder (optional accessory).

If the spindle holder is to be produced in-house:

- Contact Nakanishi Jaeger GmbH.
- Request the tolerances and production plan for the spindle holder.
- Produce the spindle holder from a thermally-conductive material (e.g. aluminum).
- Observe the dimensions of the clamping range in the Technical Specifications [> 16] section. Make sure that the HF spindle is enclosed by the spindle holder to the specified length.
- Add cooling fins or holes (greater heat dissipation) to the external surface of the spindle holder.





5.4

For guidelines on air quality, see "Air purity classes (ISO 8573-1) [▶ 28]" section.

5.5

5.6

Sealing air

The sealing air prevents foreign bodies such as chips and liquids (e.g. emulsions) from entering the HF spindle.

Check that air escapes at the front between the housing and the rotating parts of the HF spindle.

Taper cleaning

Taper cleaning prevents chips and liquids from entering the shaft during a tool change and causing contamination and damage to the inner taper and the clamping system.

The taper cleaning is integrated in the pneumatics system for the tool change. This means that no additional connections are required.

□ Blow air through collet during tool change

Pneumatic tool change

The tool change or tool taper change is performed pneumatically.

During this, a mechanism is operated inside the HF spindle which clamps, releases, or ejects the tool taper or collet.

For guidelines on air quality, see "Air purity classes (ISO 8573-1) [▶ 28]" section.



Bearings	Hybrid ball bearing (pcs)	3
	Lifetime lubricated	maintenance free

Power values Spindle holder cooled

6

	Pmax./5s	S6-60%	S1-10	00%
Rated power	0,75	0,65	0,51	[kW]
Torque	0,12	0,103	0,09	[Nm]
Voltage	71	71	63	[V]
Current	13,6	11,8	10,7	[A]

Power values Compressed air cooled

	Pmax./5s	S6-60%	S1-10	0%
Rated power	0,4	0,32	0,23	[kW]
Torque	0,121	0,077	0,066	[Nm]
Voltage	36	36	36	[V]
Current	13,6	10	9	[A]
Current	13,6	10	9	[A

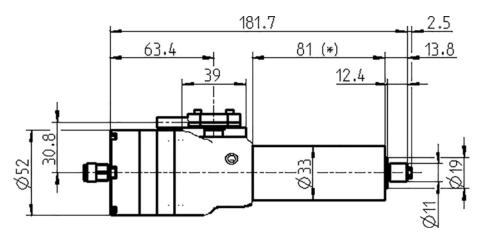
Motor data

Current	13,6	10	9	[A]
Motor technology		•	asynchronou brushes or s	
Frequency			1	.667 Hz
Motor poles (pairs)				1
Rated rotation speed			100.0	00 rpm
Acceleration/braking value Per second		(other valu	10 0 ues by consu	00 rpm ltation)



Characteristics	Housing	Stainless steel/aluminium
	Housing diameter	33 mm
	Cooling	Compressed air cooled
	Heat dissipation	Via the housing
	Housing temperature	< + 60° C
	Ambient temperature	+ 10°C + 45°C
	Sealing air	
	Protection category	IP54
	(sealing air turned on)	T JT
	Blow air through collet during tool change	
	Contact by touch	
	Tool change	Pneumatic direct change
	Collet type	5,1P-5°
	Clamping range up to	4 mm
	Clockwise	
	Connection	Cable length 1,5 m
	Weight	~ 0,8 kg
	Inner taper run out	< 1 µ

6.1 Dimensions



(*) = Clamping range



6.2

The power values (S1, S6, S2) are valid for sinusoidal currents and voltages.

The power values of the HF spindle are dependent on the frequency converter used and may vary from the indicated values.

Motor data Spindle characteristic curve 1032 Motor technology AC Motor ACM 26/15/38-2 Motor type Rated power 0,51 kW 100.000 rpm Rated rotation speed Spindle holder cooled Cooling (liquid-cooled spindle holder) < 110 °C Motor temperature Winding resistance (phase-phase) 0,219 Ω 159 W – max. (S1) Power dissipation

Measured values: S1-100%

Rated rotation speed	15 000	30 000	40 000	50 000	60 000	80 000	100 000	rpm
Speed	11 492	26 242	36 068	46 016	55 951	75 989	97 018	rpm
Frequency	250	500	667	833	1 000	1 333	1 667	Hz
Rated power	0,108	0,232	0,314	0,389	0,441	0,510	0,416	kW
Torque	0,0897	0,0843	0,0831	0,0807	0,0753	0,0641	0,0409	Nm
Voltage	18	28	35	42	47	57	63	V
Current	10,7	10,7	10,7	10,5	10,0	9,3	6,9	А
cos φ	0,87	0,81	0,80	0,79	0,80	0,79	0,79	

Measured values: S6-60%

Rated rotation speed	15 000	30 000	40 000	50 000	60 000	80 000	100 000	rpm
Speed	10 787	25 730	35 624	45 534	55 418	75 432	95 691	rpm
Frequency	250	500	667	833	1 000	1 333	1 667	Hz
Rated power	0,116	0,254	0,342	0,43	0,497	0,59	0,656	kW
Torque	0,1026	0,0941	0,0917	0,0901	0,0856	0,0747	0,0655	Nm
Voltage	19	30	37	44	49	60	71	V
Current	11,8	11,8	11,7	11,6	11,1	10,3	9,7	А
cos φ	0,89	0,82	0,8	0,78	0,79	0,79	0,78	



Measured values: S2-Pmax./5 s

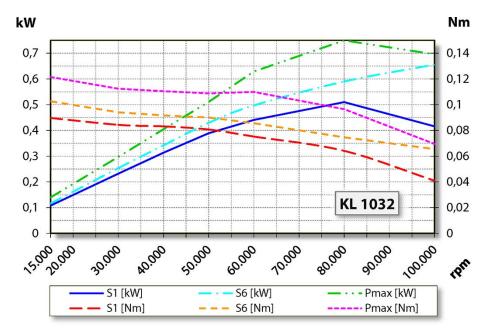
Rated rotation speed	15 000	30 000	40 000	50 000	60 000	80 000	100 000	rpm
Speed	11 000	25 216	35 005	44 872	54 645	74 220	95 614	rpm
Frequency	250	500	667	833	1 000	1 333	1 667	Hz
Rated power	0,14	0,297	0,405	0,511	0,629	0,75	0,696	kW
Torque	0,1215	0,1125	0,1105	0,1087	0,1099	0,0965	0,0695	Nm
Voltage	20	31	38	45	51	62	71	V
Current	13,6	13,6	13,6	13,6	13,0	12,9	10,1	А
cos φ	0,89	0,84	0,82	0,8	0,84	0,8	0,78	

Note on operation with static frequency converters:

For operation with a frequency converter, the effective fundamental voltage must correspond to the specified motor voltage.

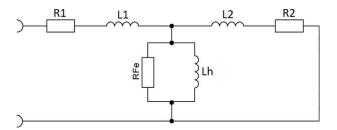
The measured currents may be greater than the specified values due to the harmonic content.

6.2.1 Performance Diagram



6.2.2









Note: Damage due to incorrect performance data.

The values of the parameters relate exclusively to the motor.

▶ HF spindle values: See tables S1-100%, S6-60% and S2-Pmax.

Parameter*	Meaning	Value	Unit
p0304	Rated voltage (phase-phase)	57	Vrms
p0305	Rated current	9,3	Arms
p0307	Rated power	0,51	kW
p0308	Rated power factor	0,79	cos φ
p0310	Rated frequency	1.000	Hz
p0311	Rated speed	80.000	rpm
	Rated power loss	159	W
	Rated rotation speed	100.000	rpm
p0312	Rated torque	0,064	Nm
p0314	Motor poles (pairs)	1	
p0320	Rated magnetization current	4,04	Arms
p0322	Maximum speed	100.000	rpm
p0326	Stalling torque correction factor	100	%
p0335	Cooling type	Spindle hol	der cooled
p0341	Moment of inertia	0,0000029	kgm²
p0348	Field weakening operating speed VDC=600V	540.818	rpm
p0350	Stator resistance, cold (strand)	0,219	Ω
p0353	Series inductance (strand)	0	mH
p0354	Rotor resistance, cold	0,16	Ω
p0356	Stator stray inductance	0,048	mH
p0358	Rotor stray inductance	0,107	mH
p0360	Main inductance	0,82	mH
p0604	Motor temperature warning threshold	90	°C
p0605	Motor temperature fault threshold	110	°C
p0640	Current limit	13	Arms
p1800	Pulse frequency	60	kHz
	DC link voltage		VDC
	Series capacitance		μF
	Maximum voltage		V
	Idle reduction		%
	Stator stray reactance X1		Ω
	Rotor stray reactance X2		Ω
	Main field reactance Xh		Ω

(*) Parameters for Siemens SINAMICS 120



6.3	Motor data							
The power values (S1, S6, S2) are valid for sinusoidal cur- rents and voltages.	Spindle characteristi	c curve					1033	
	Motor technology					A	C Motor	
The power values of the HF	Motor type					ACM 26/	/15/38-2	
spindle are dependent on the frequency converter used and	Rated power						0,23 kW	
may vary from the indicated	Rated rotation speed	b				100.	000 rpm	
values.	Cooling				Compressed air cooled			
	-	Motor temperature				, < 110 ℃		
		Winding resistance (phase-phase)				0,219 Ω		
	Power dissipation	prose pr				95 W – n		
							()	
Measured values: S1-100%	Rated rotation speed	15 000	40 000	50 000	60 000	100 000	rpm	
	Speed	12 500	36 939	47 796	56 746	97 331	rpm	
	Frequency	250	667	833	1 000	1 667	Hz	
	Rated power	0,086	0,231	0,220	0,223	0,114	kW	
	Torque	0,0658	0,0597	0,044	0,0375	0,0112	Nm	
	Voltage	17	32	33	36	34	V	
	Current	9	8,2	6,9	6,3	4,3	А	
	cos φ	0,82	0,78	0,79	0,8	0,77		
Measured values: S6-60%		45.000	10.000	50.000	<i></i>	400.000		
Measureu values. 30-00%	Rated rotation speed	15 000	40 000	50 000	60 000	100 000	rpm	
	Speed	12 111	36 263	46 246	56 164	94 200	rpm	
	Frequency	250	667	833	1 000	1 000	Hz	
	Rated power	0,098	0,275	0,323	0,294	0,212	kW	
	Torque Voltage	0,0772 18	0,0723 35	0,0666 36	0,05 36	0,0215 36	Nm V	
	Current	10	55 9,9	9,7	8,6	7,3	V A	
	cos φ	0,84	0,77	0,82	0,81	0,76	A	
	τος φ	0,01	0,77	0,02	0,01	0,70		
Measured values: S2-Pmax./ 5 s	Rated rotation speed	15 000	40 000	50 000	60 000	100 000	rpm	
	Speed	11 000	34 797	45 074	53 716	94 653	rpm	
	Frequency	250	667	833	1 000	1 667	Hz	
	Rated power	0,14	0,4	0,39	0,343	0,211	kW	
	Torque	0,1213	0,1098	0,0826	0,061	0,0213	Nm	
	Voltage	20	35	36	36	36	V	
	Current	13,6	12,8	12,6	10	7,1	А	

0,89

0,87

0,82

0,85

0,76

cos φ

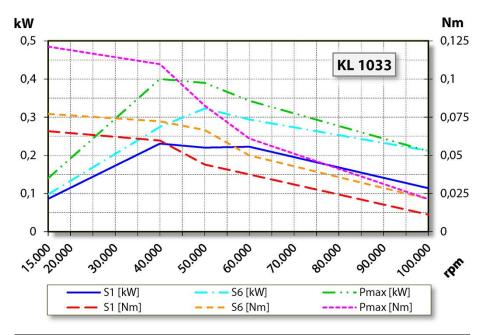


Note on operation with static frequency converters:

For operation with a frequency converter, the effective fundamental voltage must correspond to the specified motor voltage.

The measured currents may be greater than the specified values due to the harmonic content.

6.3.1 Performance Diagram



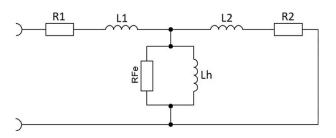
Note: Ensure functionality.

The HF spindle is cooled by the sealing air flowing through.

Always switch on the sealing air as soon as the machine enters operation.
 Sealing air temperature: max. 25°C.

If this is not observed, the HF spindle will be damaged or destroyed.

6.3.2 Equivalent circuit diagram data





Note: Damage due to incorrect performance data.

The values of the parameters relate exclusively to the motor.

▶ HF spindle values: See tables S1-100%, S6-60% and S2-Pmax.



p0304Rated voltage (phase-phase)36Vrmsp0305Rated current6,3Armsp0307Rated power223kWp0308Rated power factor0,8cos φp0310Rated frequency1.000Hzp0311Rated speed60.000rpmRated power loss95WRated rotation speed100.000rpmp0312Rated torque0,04Nmp0314Motor poles (pairs)1p0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0325Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0354Rotor resistance, cold (strand)0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold140°Cp0605Motor temperature fault threshold140°Cp0605Motor temperature fault threshold140°Cp0604Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCStator stray reactance X1ΩΩKotor stray reactance X2ΩΩ	Parameter*	Meaning	Value	Unit
protectTraceTracep0307Rated power223kWp0308Rated power factor0.8cos φp0310Rated frequency1.000Hzp0311Rated frequency1.000rpmRated power loss95WRated rotation speed100.000rpmp0312Rated torque0.04Nmp0313Rated torque0.04Nmp0320Rated magnetization current1.42Armsp0322Maximum speed100.000rpmp0335Cooling typeCompressed air cooledp0341Moment of inertia0,0000029kgm²p0353Scoling typeCompressed air cooledp0344Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0354Rotor resistance, cold (strand)0,096mHp0355Stator stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature fault threshold140°Cp0605Motor temperature fault threshold140 <t< td=""><td>p0304</td><td>Rated voltage (phase-phase)</td><td>36</td><td>Vrms</td></t<>	p0304	Rated voltage (phase-phase)	36	Vrms
protectTable partp0308Rated power factor0,8cos φp0310Rated frequency1.000Hzp0311Rated speed60.000rpmRated opwer loss95WRated rotation speed100.000rpmp0312Rated torque0,04Nmp0313Rated magnetization current1,42Armsp0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0354Rotor resistance, cold (strand)0,07mHp0358Rotor stray inductance0,096mHp0350Main inductance0,097mHp0351Rotor temperature warning threshold90°Cp0604Motor temperature fault threshold140°Cp0605Motor temperature fault threshold140°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVVIdle reduction%Stator stray reactance X1Ω	p0305	Rated current	6,3	Arms
p0310Rated frequency1.000Hzp0311Rated speed60.000rpmRated power loss95WRated rotation speed100.000rpmp0312Rated torque0,04Nmp0314Motor poles (pairs)1p0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0354Rotor resistance, cold (strand)0,016Ωp0358Rotor stray inductance0,096mHp0360Main inductance0,097mHp0604Motor temperature varning threshold90°Cp0605Motor temperature fault threshold140°Cp0605Motor temperature fault threshold140°Cp0605Motor temperature fault threshold140°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVVIdle reduction%Stator stray reactance X1Ω	p0307	Rated power	223	kW
p0311Rated speed60.000rpmRated power loss95WRated rotation speed100.000rpmp0312Rated torque0,04Nmp0314Motor poles (pairs)1p0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,997mHp0360Main inductance0,997mHp0360Motor temperature warning threshold90°Cp0604Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCKator stray reactance X1%	p0308	Rated power factor	0,8	cos φ
Rated power loss95WRated rotation speed100.000rpmp0312Rated torque0,04Nmp0314Motor poles (pairs)1p0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0341Moment of inertia0,0000029kgm²p0350Stator resistance, cold (strand)0,219Ωp0354Rotor resistance, cold (strand)0,16Ωp0355Stator stray inductance0,096mHp0360Main inductance0,997mHp0360Motor temperature warning threshold90°Cp0604Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCVDCIdle reduction%Stator stray reactance X1Ω	p0310	Rated frequency	1.000	Hz
Rated rotation speed100.000rpmp0312Rated torque0,04Nmp0314Motor poles (pairs)1p0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0341Moment of inertia0,0000029kgm²p0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,096mHp0360Main inductance0,997mHp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCVDCSeries capacitanceµFMaximum voltageVStator stray reactance X1Ω	p0311	Rated speed	60.000	rpm
p0312Rated torque0,04Nmp0314Motor poles (pairs)1p0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0341Moment of inertia0,000029kgm²p0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,096mHp0356Stator stray inductance0,997mHp0360Main inductance0,997mHp0604Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCVDCSeries capacitance X1%		Rated power loss	95	W
p0314Motor poles (pairs)1p0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0341Moment of inertia0,0000029kgm²p0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCVCIdle reduction%Stator stray reactance X1Ω		Rated rotation speed	100.000	rpm
p0320Rated magnetization current1,42Armsp0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0341Moment of inertia0,0000029kgm²p0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,07mHp0356Stator stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature fault threshold90°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCKatimum voltageVIdle reduction%Stator stray reactance X1Ω	p0312	Rated torque	0,04	Nm
p0322Maximum speed100.000rpmp0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0341Moment of inertia0,0000029kgm²p0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,097mHp0356Stator stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCKatimum voltageVStator stray reactance X1 Ω	p0314	Motor poles (pairs)	1	
p0326Stalling torque correction factor100%p0335Cooling typeCompressed air cooledp0341Moment of inertia0,000029kgm²p0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,07mHp0356Stator stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzSeries capacitanceµFMaximum voltageVIdle reduction%Stator stray reactance X1Ω	p0320	Rated magnetization current	1,42	Arms
p0335Cooling typeCompressed air cooledp0341Moment of inertia0,0000029kgm²p0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,07mHp0358Rotor stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCKarimum voltageVIdle reduction%Stator stray reactance X1Ω	p0322	Maximum speed	100.000	rpm
p0341Moment of inertia0,0000029kgm²p0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,07mHp0356Stator stray inductance0,096mHp0358Rotor stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0640Current limit10Armsp1800Pulse frequency60kHzSeries capacitanceµFMaximum voltageVIdle reduction%Stator stray reactance X1Ω	p0326	Stalling torque correction factor	100	%
p0348Field weakening operating speed VDC=600V707.107rpmp0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,07mHp0358Rotor stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCIdle reduction%Stator stray reactance X1Ω	p0335	Cooling type	Compressed	air cooled
p0350Stator resistance, cold (strand)0,219Ωp0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,07mHp0358Rotor stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCMaximum voltageVIdle reduction%Stator stray reactance X1Ω	p0341	Moment of inertia	0,0000029	kgm²
p0353Series inductance (strand)0mHp0354Rotor resistance, cold0,16Ωp0355Stator stray inductance0,07mHp0358Rotor stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceµFIdle reduction%Stator stray reactance X1Ω	p0348	Field weakening operating speed VDC=600V	707.107	rpm
p0354Rotor resistance, cold0,16Ωp0356Stator stray inductance0,07mHp0358Rotor stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceµFIdle reduction%Stator stray reactance X1Ω	p0350	Stator resistance, cold (strand)	0,219	Ω
p0356Stator stray inductance0,07mHp0358Rotor stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceµFIdle reduction%Stator stray reactance X1Ω	p0353	Series inductance (strand)	0	mH
p0358Rotor stray inductance0,096mHp0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceμFIdle reduction%Stator stray reactance X1Ω	p0354	Rotor resistance, cold	0,16	Ω
p0360Main inductance0,997mHp0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceµFIdle reduction%Stator stray reactance X1Ω	p0356	Stator stray inductance	0,07	mH
p0604Motor temperature warning threshold90°Cp0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceµFMaximum voltageVIdle reduction%Stator stray reactance X1Ω	p0358	Rotor stray inductance	0,096	mH
p0605Motor temperature fault threshold140°Cp0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceμFMaximum voltageVIdle reduction%Stator stray reactance X1Ω	p0360	Main inductance	0,997	mH
p0640Current limit10Armsp1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceμFMaximum voltageVIdle reduction%Stator stray reactance X1Ω	p0604	Motor temperature warning threshold	90	°C
p1800Pulse frequency60kHzDC link voltageVDCSeries capacitanceμFMaximum voltageVIdle reduction%Stator stray reactance X1Ω	p0605	Motor temperature fault threshold	140	°C
DC link voltageVDCSeries capacitanceμFMaximum voltageVIdle reduction%Stator stray reactance X1Ω	p0640	Current limit	10	Arms
Series capacitance μF Maximum voltage V Idle reduction % Stator stray reactance X1 Ω	p1800	Pulse frequency	60	kHz
Maximum voltage V Idle reduction % Stator stray reactance X1 Ω		DC link voltage		VDC
Idle reduction % Stator stray reactance X1 Ω		Series capacitance		μF
Stator stray reactance X1 Ω		Maximum voltage		V
		Idle reduction		%
Rotor stray reactance X2 Ω		Stator stray reactance X1		Ω
		Rotor stray reactance X2		Ω
Main field reactance Xh Ω		Main field reactance Xh		Ω

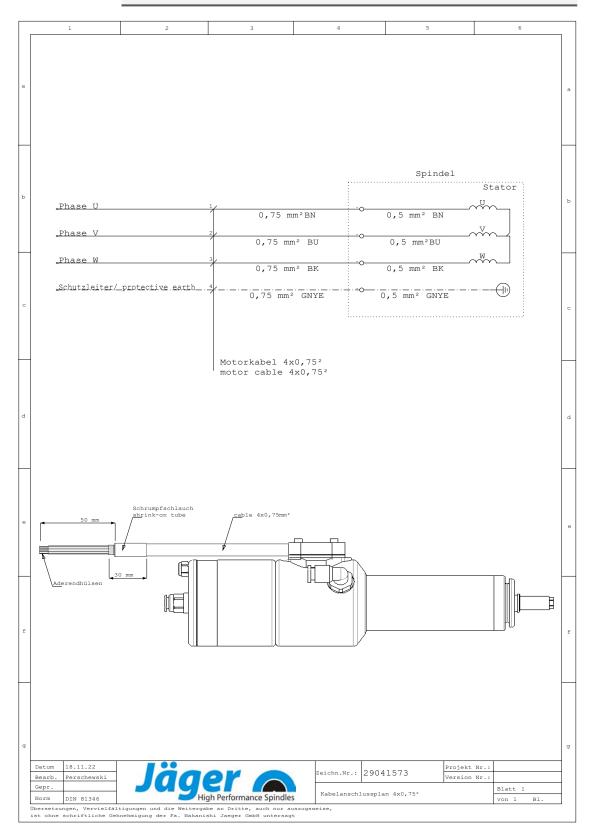
(*) Parameters for Siemens SINAMICS 120



6.4 Wiring diagram

Note: Do not change the ex-works configuration.

Any change may cause overvoltage on the electrical components (e.g. PTC, differential magneto resistor).





6.5 Touch

The contact signal is produced by establishing an electrically conductive connection between the rotating shaft of the HF spindle and the motor casing.

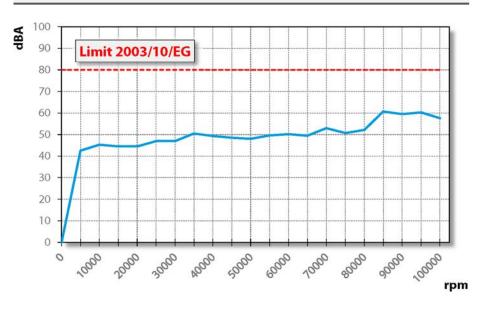
- When the tool comes into contact with the workpiece, the signal can be evaluated by the machine.
- □ The signal also acts as ESD protection during machining.
- □ The wear on the sliding contact is not monitored.

Air-borne noise emissions



CAUTION: Noise has an impact on health.

• Only operate the HF spindle if you are wearing hearing protection.









Operating location

Operating location

DANGER: Due to flying parts.

If the HF spindle is incorrectly attached, it may come loose during operation and be flung away by the forces that occur.

Clamp the HF spindle firmly.

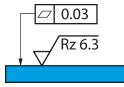
WARNING: Risk of injury due to flying parts.

The HF spindle operates at high speeds which may cause chips to fly out with great force.

- ▶ Never remove the protective devices of the machine or system.
- Always wear protective goggles during work.

Note the following points before installing the HF spindle:

- Make sure that the correct spindle holder for the HF spindle is fitted in the machine.
- Check the connecting hoses for damage.
- Check the connecting cables for damage.
- Only use undamaged hoses and cables.
- Do not allow the HF spindle to run in the vicinity of a heat source.



Example of design: Mounting surface



Installation

8

Before installation:

Check the HF spindle for damage and ensure that it is complete.

If the HF spindle has been stored for a long period:

Carry out all steps in the Commissioning after storage section.

Installing the HF spindle

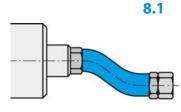
Complete the following steps in sequence to install the HF spindle:

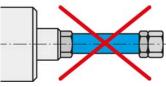
- Remove the sealing plugs that protect the connections against damage and contamination during transportation.
- Instead of these sealing plugs, install the appropriate hose fittings.
- Install the corresponding hoses in the hose fittings
- S Make sure that the connections are flexible and free of strain.
- Seal all connections for compressed air axially in relation to the tightening direction.
- If the HF spindle is equipped with sealing air:
 - Solution Wake sure that no air flow can occur in the bearing area.
 - Always use sealed cable boxes when connecting electrical lines.
- Mount the HF spindle on the machine.
- Connect the hoses to the connection of the respective media.
- Remove the protective cap that protects the shaft against damage and contamination during transportation.
- Connect the connector of the operating connection lines to the relevant connection of the HF spindle and to the frequency converter.
- Lock the connectors.

Diameter of media supply line

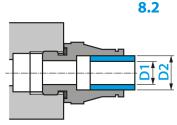
The nominal size of the media supply lines can be found in the following table:

DN	Medium	D1		D	2
2.8	Compressed air	2.8 mm	⁷ / ₆₄ "	4 mm	⁵ / ₃₂ "
4	Compressed air	4 mm	⁵ / ₃₂ "	6 mm	¹⁵ / ₆₄ "
6	Compressed air	6 mm	¹⁵ / ₆₄ "	8 mm	⁵ / ₁₆ "





Connect media and cables with a flexible connection.





Installation

8.3 Compressed air

8.3.1 Air purity classes (ISO 8573-1)

Solid impurities	Class 3 Filter grade at least 5 μm for solids
Water content	Class 4 Max. pressure dew point +3 °C
Total oil content	Class 3 Max. oil content 1 mg/m ³

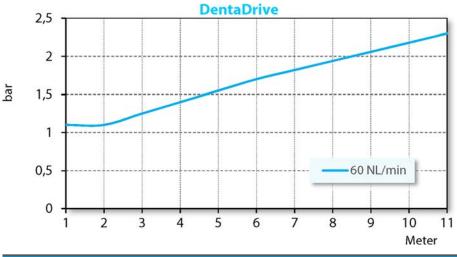
8.3.2

For guidelines on air quality, see "Air purity classes (ISO 8573-1) [▶ 28]" section.

Setting the sealing air

The adjustment value for the sealing air depends on the hose diameter and length.

- Hose diameter: DN 4
- The setting value can be found in the following diagram.
- To ensure effective control, turn on the sealing air and cooling when turning on the machine. This protects the HF spindle even when it is stationary.



Note: Ensure functionality.

The HF spindle is cooled by the sealing air flowing through.

- Always switch on the sealing air as soon as the machine enters operation.
- □ Sealing air temperature: max. 25°C.

If this is not observed, the HF spindle will be damaged or destroyed.



Installation

8.3.3

For guidelines on air quality, see "Air purity classes (ISO 8573-1) [▷ 28]" section. Skeep to the following values:

Setting values

Pneumatic system for tool change

4,5 ±0,5 bar





Commissioning

Commissioning

DANGER: Due to flying parts.

If the speed is selected incorrectly, the HF spindle or the tool may be destroyed and their fragments may be flung out.

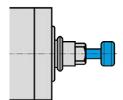
- Note the maximum speed for the selected tool.
- Note the maximum speed for the HF spindle.
- The maximum permissible speed of the HF spindle for commissioning / processing is always the lowest specified speed.

Note: Ensure functionality.

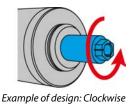
Never operate the HF spindle without a clamped tool shank.

If no tool shank is clamped:

- □ The clamping system is damaged by the centrifugal forces.
- □ The clamping system is shifted.
- □ The balance of the HF spindle is affected.
- □ The bearing is damaged.
- **Turn the shaft of the spindle at least ten times by hand.**



Example of design: Inserting the shank



9.1

10

2 2

Duration of load (minutes)

Running-in schedule

- Put the HF spindle into operation with a clamped tool (without machining) for approx. 10 minutes.
- The speed in this case should be no more than 20% of the maximum permissible speed for the HF spindle.
 - bee definition: Max. permissible speed
- Allow the HF spindle to run for approx. 2 minutes at a maximum of 50% of the maximum permissible speed.
- Operate the HF spindle for approx. 2 more minutes at a maximum of 80% of the maximum permissible speed.

The HF spindle is now ready for operation.



Commissioning

9.2 Daily start-up

Proceed as follows to preheat the grease lubrication of the bearing and to protect it:

- Operate the HF spindle with a clamped tool (without machining).
 - Section Approx. 2 minutes.
 - At maximum 50 % of the maximum permissible speed. (See Commissioning [> 30] section)

This brings the HF spindle to its operating temperature.

9.3 Shutdown signal

Use the option on the frequency converter of detecting the shutdown signal from the shaft and forwarding this to the machine controller for evaluation.

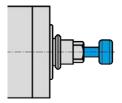
9.4 Commissioning after storage

- Do not put the HF spindle into operation until its temperature has adjusted from the temperature of the storage location to the temperature of the usage location.
 - The temperature difference between the HF spindle and the usage location should not exceed 10°C.
- Carry out all steps in the "Maintenance [▶ 36]" section.
- Operate the HF spindle at a maximum of 50 % of the max. permissible speed for approx. 5 minutes.
 - See Commissioning [> 30] section
- Operate the HF spindle for approx. 2 more minutes at a maximum of 80 % of the maximum permissible speed.

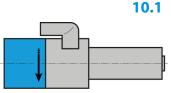
This preheats the grease lubrication of the bearing and protects it.







Example of design: Inserting the shank



Sample illustration: Direction of rotation indication

10.2

Tool change

Tool change

CAUTION: Danger of being drawn in by rotating shaft.

If the shaft is still rotating, fingers and hands may be drawn in and crushed.Only change the tool if the shaft is at a standstill.

Note: Ensure functionality.

Never operate the HF spindle without a clamped tool shank.

If no tool shank is clamped:

- □ The clamping system is damaged by the centrifugal forces.
- □ The clamping system is shifted.
- □ The balance of the HF spindle is affected.
- □ The bearing is damaged.

Clockwise

The HF spindle clamping system is designed for clockwise rotation.

- Only use tools with the correct direction of rotation for the HF spindle.
- Only use tool mounts with the correct HF spindle direction of rotation.
- Set the direction of rotation of the HF spindle on the FC in accordance with the arrow display on the HF spindle.

Pneumatic direct change

Tip: Ensure concentric run-out quality.

- Keep collet, clamping nut, contact surface, shaft, tool taper, and tool mount clean at all times.
- When transporting the HF spindle, always fit an appropriate shank in the collet.
- Make sure that the shaft of the HF spindle has come to a complete standstill.
- Switch on the compressed air for the tool change.
- Remove the tool.
- Clean the inner taper of the tool mount and the inner taper of the shaft with the felt cleaning taper.
- Insert the tool.
- Switch off the compressed air for the tool change.
- S Wait for 1-2 seconds after completing the tool change.
- Start the HF spindle.



Tool change

10.2.1 Changing the collet

Proceed as follows to change the collet:

- Switch on the compressed air for the tool change.
- Remove the tool.



Note: Ensure functionality.

Never close the collet without a clamped tool shank.

If no tool shank is clamped:

- □ The clamping system is damaged.
- Insert a suitable tool shank into the collet.
- Screw the collet out of the shaft of the HF spindle using the screw-in tool.

Tip: Ensure concentric run-out quality.

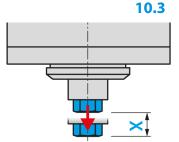
- Make sure that there is no contamination in the collet and that no contamination occurs during cleaning.
- Clean the inner taper of the shaft with the felt cone from the service set.
- Clean the collet with the brush.
- Apply a light greasy film to the taper of the collet. To do this, only use the collet grease from the service set.
- Insert a suitable tool shank into the collet.
- Screw the collet as far as possible into the shaft using the screw-in tool.
 ♦ Tightening torque M_A max.: 0.5 Nm
- Switch off the compressed air for the tool change.

Tip: Check the tool change.

- Activate the tool change 2-3 times.
- Check the fit of the collet.
 - Solution Tighten the collet if necessary.
- Switch on the compressed air for the tool change.
- Remove the shank from the collet.
- Insert the tool.
- Switch off the compressed air for the tool change.

The HF spindle is now ready for operation.





Example of design: Ejection travel

10.3.1

Tool changing station (optional accessory)

During a tool change, the HF spindle moves into the changing station with the clamped tool.

Note the following values when producing the changing station in order to compensate for the ejection travel (X):

Spring loaded	X = 2 - 5 mm
Spring force	40 - 80 N

pneumatic direct change

Tool change

The HF spindle enters the changing station as far as the stop ring. Only then does the cylinder push the collet out of the shaft.

- The collet opens.
- Only the tool is deposited in the changing station.

Tip: Fast tool change.

Use a tool with a stop ring.

This means that there is no need to re-adjust the immersion depth after each tool change.

Installing the changing station

Proceed as follows to install the changing station:

- Drill a hole with a suitable diameter (Ø D1 H7) for the tool mount.
- Add an M5 thread.
- Insert the changing station into the hole.
- Secure the changing station using the threaded spindle (M5).

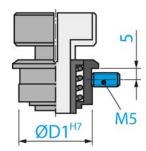
10.3.3

10.3.2

Maintenance

Before commencing work:

- Check that all surfaces are thoroughly cleaned and free of dust, grease, coolant, machining residues, and metal particles.
- Check that the changing station is free of damage.







Tools for high speed cutting

DANGER: Due to flying parts.

If the wrong direction of rotation is used, the tool is damaged when load is applied. The centrifugal forces cause the broken part to be flung out.

Only use tools with the correct direction of rotation for the HF spindle.



DANGER: Due to flying parts.

If the speed is selected incorrectly, the HF spindle or the tool may be destroyed and their fragments may be flung out.

- Note the maximum speed for the selected tool.
- Note the maximum speed for the HF spindle.
- The maximum permissible speed of the HF spindle for commissioning / processing is always the lowest specified speed.
- Only use tools that are technically sound.
- Only use tools with a tool shank diameter that corresponds to the inner diameter of the collet. For example, do not use shanks with a diameter of 3 mm in collets for 1/8" (=3.175 mm).
 - ♦ Also see the Technical Specifications [▶ 16] section
- Only use tool shanks with a diameter tolerance of h6.
- Do not use tool shanks with a clamping surface (e.g. Weldon).
- Only use a balanced tool.
 DIN ISO 1940, balance grade 2,5.

Broken-off tool

CAUTION: Risk of burns.

The broken-off tool may be hot.

Use gloves to protect against injury.

Remove the remains of the broken-off tool from the collet using the ejector pin from the service set.

Proceed as follows:

Remove the collet from the shaft of the HF spindle.

Inside the collet there is a stop screw with a hole.

- Insert the ejector pin through this hole.
- Push the broken-off tool forward out of the collet using the ejector pin.
- Clean the collet.
- Insert the collet back into the HF spindle shaft.



11.1



Maintenance

Only specialist personnel may perform maintenance on the spindle.

The HF spindle must be shut down before any maintenance work.

- Make sure that the shaft of the HF spindle has come to an absolute standstill.
- Before carrying out any work, read the corresponding section of the manual carefully again.
- Observe the manual of the machine in which the HF spindle is installed.
- Observe all safety instructions and safety rules.

12.1 Ball bearings



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Note: Foreign matter reduces the service life.

The HF spindle bearings have lifetime grease lubrication. This means that they do not require maintenance.

- Do not lubricate the ball bearings.
- Do not apply grease, oil, or cleaning agents to the openings of the HF spindle.

12.2 Daily cleaning

To ensure that the HF spindle functions safely and accurately, all contact surfaces of the HF spindle, the mount for the HF spindle, the tool mount, and the tool holder must be clean.

Note: Foreign matter reduces the service life.

- Do not use compressed air to clean the HF spindle.
- ▶ Do not use ultrasonic cleaning on the HF spindle.
- Do not use steam jets to clean the HF spindle.

This could cause contamination to enter the bearing area.

12.2.1 Before commencing work

- Check that all surfaces are thoroughly cleaned and free of dust, grease, coolant, machining residues, and metal particles.
- Check that the HF spindle is free of damage.
- If the HF spindle is equipped with sealing air, always switch this on during cleaning.
- Only use a clean, soft cloth or a clean, soft brush for cleaning.

12.2.2 With every tool change

- Ensure that the tool mount and tool shank are clean.
 - ✤ Remove any soiling.





Maintenance

12.2.3 Every time the clamping device is changed

- Clean the inner taper of the HF spindle shaft. The inner taper must be free of chips and contamination.
- Clean the tool taper.
- Apply a light greasy film to the taper of the collet after cleaning.
 - Solution of the collet grease from the service set.

This improves the sliding movement and increases the clamping force of the collet.

12.3 In the case of storage

If the HF spindle is not required for a prolonged period of time:

- Store the HF spindle in horizontal position.
- Store the HF spindle so that it is protected from moisture, dust, and other environmental influences.
- Note the following storage conditions.

Temperature of storage location	+10°C + 60° C
Relative humidity	< 50 %

12.4 Monthly maintenance

Turn the shaft of the HF spindle at least ten times by hand every four weeks.

12.5 Long periods of storage

- Turn the shaft of the HF spindle at least ten times by hand every three months.
- Then put the HF spindle into operation with a tool inserted for approx.
 10 minutes.
 - The speed should be no more than 20 % of the maximum permissible speed for the HF spindle. (See Commissioning [> 30] section)

12.6 Maximum storage time

The maximum storage time is 2 years.

Make sure that all information in the "Long periods of storage [> 37]" section is adhered to. This is the only way in which to maintain the functionality of the HF spindle.



Dismantling

Dismantling

Proceed as follows to remove the HF spindle:

- Completely disconnect the power supply.
- **Completely disconnect the media supply (air and liquid).**
- Make sure that the shaft of the HF spindle has come to an absolute standstill.
- Remove all connections from the HF spindle.
- **C** Remove the HF spindle from the machine.



13

Disposal and environmental protection

More than 90% of the materials used in the HF spindle can be recycled (aluminum, stainless steel, steel, copper, etc.)

The HF spindle may not be disposed of with normal domestic waste.

- Remove all non-recyclable materials.
- Dispose of the HF spindle as scrap at an approved recycling facility.
- Follow all rules of the responsible administrative bodies.

If the HF spindle cannot be dismantled, send the HF spindle to **Nakanishi** Jaeger GmbH. Nakanishi Jaeger GmbH shall not assume the costs incurred for shipment and the fees for the recycling facilities.





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Service and repairs

DANGER: Electric shock.

Electric shock can lead to severe burns and life-threatening injuries.

Take measures to prevent hazards caused by electrical energy (for details refer e.g. to the regulations issued by the VDE and the local energy supply companies).

Before commencing work, switch off the power supply of the HF spindle.



Note: Damage due to electrostatic discharge.

Do not touch the electrostatic-sensitive components of the HF spindle.

14.1 Service partners

Only certified service partners may open and repair the spindle. Failure to comply with this voids any warranty claims and compensation claims for damages.

C The list of partners can be found on the following website.

https://www.nakanishi-jaeger.com/en/contact/service-partners



14.2

HF spindle not rotating

Malfunctions

The list below can be used to quickly investigate and eliminate faults.

Cause	Troubleshooting
No power supply	 Check the frequency converter. Check the machine. Check all electrical connections. Check all wires in the motor cable.
	 Activate the Start/Reset button. Wait until the HF spindle has cooled down.
Thermal protection has been activated	 Check the frequency converter for error messages. If no messages are illuminated, start the frequency converter. (See also "Spindle becomes hot [> 40]".)
Frequency converter has shut down	 Check the error messages in the frequency converter man- ual.
Tool change initiated	Turn off the pneumatic system for the tool change.

HF spindle becomes hot

Cause	Troubleshooting
	Check the power of the chiller.
	Check the water level of the chiller.
Insufficient cooling	Check the connections and the cooling hoses.
	Check the cooling circuit.
	Check the chiller for error messages.
Phase missing	□ Check all wires in the motor cable for cable breaks.
	□ Check the rotational direction of the HF spindle.
Machining too boow	Check the rotational direction of the tool.
Machining too heavy	Check the tool for damage.
	Reduce the machining load intensity.
Frequency converter incorrectly set	Compare the values for the HF spindle with the set values on the frequency converter.



Service and repairs

HF s	pindle	becomes	loud

Cause	Troubleshooting
Tool unsuitable	 Only use balanced tools. (Also see the "Tools for high speed cutting [> 35]" section.) Check the tool for damage. Replace damaged tool.
HF spindle is not clamped truly or is dis- torted	Only use spindle holders from the original accessories or holders produced according to the tolerances specified by Nakanishi Jaeger GmbH.
HF spindle clamped too tightly	 Only tighten the clamping screws of the spindle holder manually. Do not use technical aids to clamp the HF spindle.
Bearings damaged	Contact Nakanishi Jaeger GmbH service.
Cause	Troubleshooting
Contoniostica	Remove all contamination between the tool taper and shaft of the HF spindle.

No automatic tool change

Contamination	 Remove all contamination between the tool taper and shaft of the HF spindle.
	(Observe all points in the "Tool change [▶ 32]" and "Mainte- nance [▶ 36]" sections.)
	□ Check the electrical connection of the cylinder.
Collet does not open	(Observe all points in the "Tool change [> 32]" and "Mainte- nance [> 36]" sections.)

Sensor does not send any signals

Cause	Troubleshooting
No connection to sen- sor	Check the lines and connections.



HF spindle vibrates/ oscillates

Service and repairs

Cause	Troubleshooting
Tool unsuitable	 Only use balanced tools. (Also see the "Tools for high speed cutting [> 35]" section.) Check whether the tool is suitable for the application. Check the tool for damage. Replace damaged tool.
Contamination	 Remove all contamination between the tool taper and shaft of the HF spindle. (Observe all points in the "Tool change [> 32]" and "Maintenance [> 36]" sections.)
Frequency converter incorrectly set	Compare the values for the HF spindle with the set values on the frequency converter.
Machining too heavy	Reduce the machining load intensity.
Mounting screws are loose	Tighten the screws securely.
HF spindle damaged	Contact Nakanishi Jaeger GmbH service.

If the error is not rectified after checking all of the points, contact the relevant service partner.

- **C** Request the accompanying note for the repair from the service partner.
- Check the manual of the machine.
- **Contact the manufacturer of the machine.**



Declaration of Incorporation

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The safety instructions of the product documentation supplied must be observed.

Declaration of Incorporation Under the EC Machinery Directive

Nakanishi Jaeger GmbH

SF-Elektromaschinenbau Siemensstr. 8 D-61239 Ober-Mörlen Tel. +49 (0) 60029123 -0

hereby declare that the product,

Product	High Frequency Spindle
Туре	DentaDrive X.0
Serial no.	See last page of manual

as far as possible from the supplied, complies with the essential requirements of the Machinery Directive 2006/42/EC.

Sections of the Machinery Directive have been applied: 1.1.1; 1.1.2; 1.1.5; 1.3.2; 1.3.4; 1.5.1; 1.5.2; 1.5.4; 1.5.5; 1.5.6; 1.5.8; 1.5.9; 1.6.4; 1.6.5; 1.7.1; 1.7.1.1; 1.7.2; 1.7.3; 1.7.4;

The incomplete machinery in its standard design complies furthermore with the following applicable regulations:

Applicable harmonized standards

DIN EN ISO 12100 Safety of machines

The machinery is incomplete and must not be put into service until the machinery into which it is to be incorporated has been declared in conformity with the provisions of the Machinery Directive 2006/42/EC and any other applicable regulations.

We at Nakanishi Jaeger GmbH agree to submit the special documents for incomplete machines to national authorities upon request.

The special technical documentation referred to in Annex VII, Part B, belonging to the machine has been created.

Person who is authorized to compile the documents listed in Annex VII, Part B:

Nakanishi Jaeger GmbH

Ober-Mörlen, 01.09.2023



Nakanishi Jaeger YouTube channel

Scan this QR code with any QR code scanner.



Nakanishi Jaeger GmbH

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